

CLAIMS

1. A method to locate a fault from one end of a section of a power line (A-B) by means of measurements of current, voltage and angles between the phases at a first (A) end of said section, and that upon detection of a fault condition between said first end and a second end of said power line, **characterised by**

-calculating symmetrical components of currents for said current and voltage measure at said first end,
10 -calculating a distance (d) from said first end (2) to the fault (F) the distance (d) to the fault using a quadratic equation of the form:

$$B_2 d^2 + B_1 d + B_0 = 0$$

where:

15 $B_2 = A_{2_Re} A_{00_Im} - A_{2_Im} A_{00_Re}$

$$B_1 = A_{1_Re} A_{00_Im} - A_{1_Im} A_{00_Re}$$

$$B_0 = A_{0_Re} A_{00_Im} - A_{0_Im} A_{00_Re}$$

2. A method according to claim 1, **characterised** by calculating the distance (d) to the fault using an equation of the form:

$$K_1 Z_{1L} d^2 + (L_1 Z_{1L} - K_1 Z_{AA_p}) d - L_1 Z_{AA_p} + R_F M_1 \frac{(a_{F1} \Delta I_{AA1} + a_{F2} I_{AA2})}{I_{AA_p}} = 0 \quad (8)$$

where:

$$Z_{AA_p} = \frac{V_{AA_p}}{I_{AA_p}} - \text{calculated fault loop impedance.}$$

25 3.. A method according to any of claims 1 or 2, **characterised** by calculating the distance (d) to the fault using an equation of the form:

$$A_2 d^2 + A_1 d + A_0 + A_{00} R_F = 0$$

where:

30 $A_2 = A_{2_Re} + j A_{2_Im} = K_1 Z_{1LA}$

$$A_1 = A_{1_Re} + j A_{1_Im} = L_1 Z_{1LA} - K_1 Z_{AA_p}$$

$$\underline{A}_0 = A_{0_Re} + jA_{0_Im} = -\underline{L}_1 \underline{Z}_{AA_p}$$

$$A_{00_Re} + jA_{00_Im} = \frac{\underline{M}_1 (\underline{a}_{F1} \underline{I}_{AA1} + \underline{a}_{F2} \underline{I}_{AA2})}{\underline{I}_{AA_p}}$$

$$\underline{Z}_{AA_p} = \frac{\underline{V}_{AA_p}}{\underline{I}_{AA_p}} = \text{calculated fault loop impedance}$$

\underline{K}_1 , \underline{L}_1 , \underline{M}_1 = coefficients gathered in TABLE 3.

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4. A method according to any of claims 1-3, **characterised** by
 -determining source impedance at said first end as a
 representative value, and
 -determining a value for source impedance at said second end
 10 as a representative value.

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5. A method according to any of claims 1-4, **characterised** by
 calculating a value for impedance of an extra link (45, 55)
 between the terminals A, B, as having impedance for the
 positive sequence equal to:

$$(\underline{Z}_{1LB \& AB} = \frac{\underline{Z}_{1LB} \underline{Z}_{1AB}}{\underline{Z}_{1LB} + \underline{Z}_{1AB}})$$

where

\underline{Z}_{1AB} = impedance for the positive sequence of the extra link,

\underline{Z}_{1LA} = positive sequence impedance of the healthy line.

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6. A method according to any of claims 1-5, **characterised** by
 calculating symmetrical components of currents for said
 current and voltage measured at said first end by:

-inputting instantaneous phase voltages (30a),

25 -filtering (33a) the values to determine the phasors, and

-calculating (34a) phasors of symmetrical components of
 voltages.

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7. A method according to any of claims 1-6, **characterised** by
 calculating symmetrical components of currents for said
 current and voltage measured at said first end by

inputting instantaneous phase currents and instantaneous zero sequence current from a healthy line(30b),

-filtering (33b) the values to determine the phasors, and
-calculating (34b) phasors of symmetrical components of

currents.

8. A method according to any of claims 1-7, **characterised** by determining a compensation for shunt capacitance by means of an equation of the form:

$$B_2^{comp-1}(d_{comp-1})^2 + B_1^{comp-1}d_{comp-1} + B_0^{comp-1} = 0 \quad (22)$$

where:

$$B_2^{comp-1} = A_{2_Re}^{comp-1}A_{00_Im}^{comp-1} - A_{2_Im}^{comp-1}A_{00_Re}^{comp-1}$$

$$B_1^{comp-1} = A_{1_Re}^{comp-1}A_{00_Im}^{comp-1} - A_{1_Im}^{comp-1}A_{00_Re}^{comp-1}$$

$$B_0^{comp-1} = A_{0_Re}^{comp-1}A_{00_Im}^{comp-1} - A_{0_Im}^{comp-1}A_{00_Re}^{comp-1}$$

9. A method according to claim 8, **characterised** by determining a compensation for shunt capacitance by means of an equation of the form:

$$\underline{A}_2^{comp-1}(d_{comp-1})^2 + \underline{A}_1^{comp-1}d_{comp-1} + \underline{A}_0^{comp-1} + \underline{A}_{00}^{comp-1}R_F = 0 \quad (21a)$$

where:

$$\underline{A}_2^{comp-1} = A_{2_Re}^{comp-1} + jA_{2_Im}^{comp-1} = \underline{K}_1\underline{Z}_{1L}$$

$$\underline{A}_1^{comp-1} = A_{1_Re}^{comp-1} + jA_{1_Im}^{comp-1} = \underline{L}_1\underline{Z}_{1L} - \underline{K}_1\underline{Z}_{A-p}^{comp-1}$$

$$\underline{A}_0^{comp-1} = A_{0_Re}^{comp-1} + jA_{0_Im}^{comp-1} = -\underline{L}_1\underline{Z}_{A-p}^{comp-1}$$

$$\underline{A}_{00}^{comp-1} = A_{00_Re}^{comp-1} + jA_{00_Im}^{comp-1} = \frac{\underline{M}_1(\underline{a}_{F1}\underline{A}_{AA1} + \underline{a}_{F2}\underline{I}_{AA2})}{\underline{I}_{A-p}^{comp-1}}$$

$$\underline{Z}_{A-p}^{comp-1} = \frac{\underline{V}_{A-p}}{\underline{I}_{A-p}^{comp-1}} - \text{fault loop impedance calculated from:}$$

\underline{V}_{A-p} - original (uncompensated) fault loop voltage,

$\underline{I}_{A-p}^{comp-1} = \underline{a}_1\underline{I}_{A1_comp-1} + \underline{a}_2\underline{I}_{A2_comp-1} + \underline{a}_0\underline{I}_{A0_comp-1}$ - fault loop current

composed of the positive (12), negative (16) and zero (17)

sequence currents obtained after deducing the respective capacitive currents from the original currents, and \underline{K}_1 , \underline{L}_1 , \underline{M}_1 = coefficients gathered in TABLE 3.

5 10. A method according to any of claims 1-9, **characterised** by measuring the source impedance \underline{Z}_{1sA} at said first end A.

11. A method according to any of claims 1-9, **characterised** by
 -measuring the source impedance \underline{Z}_{1sB} at said second end B,
 10 -sending a communication of the measured value of source impedance \underline{Z}_{1sB} at said second end B to a fault locator at said first end A.

12. A method according to any of claims 1-11, **characterised** by
 15 -determining the zero sequence current from the healthy line of a section of parallel power lines,
 -calculating a distance to a fault for the parallel line section.

20 13. A method according to claim 12, **characterised** by determining distance to a single phase to ground fault without measurements from an operating healthy parallel line by means of complex coefficients \underline{P}_0 according to a formula of the form:

$$\underline{P}_0 = \frac{\underline{Z}_{0LB} - \underline{Z}_{0m}}{\underline{Z}_{0LA} - \underline{Z}_{0m}}$$

25 and \underline{K}_1 , \underline{L}_1 , \underline{M}_1 according to

$$\underline{K}_1 = -\underline{Z}_{1LA}(\underline{Z}_{1sA} + \underline{Z}_{1sB} + \underline{Z}_{1LB})$$

$$\underline{L}_1 = -\underline{K}_1 + \underline{Z}_{1LB}\underline{Z}_{1sB}$$

$$\underline{M}_1 = \underline{Z}_{1LA}\underline{Z}_{1LB} + \underline{Z}_{1LA}(\underline{Z}_{1sA} + \underline{Z}_{1sB}) + \underline{Z}_{1LB}(\underline{Z}_{1sA} + \underline{Z}_{1sB})$$

30 14. A method according to claim 12, **characterised** by determining distance to a single phase to ground fault without

measurements from switched off and grounded parallel line by means of complex coefficients \underline{P}_0 according to

$$\underline{P}_0 = -\frac{\underline{Z}_{0LB}}{\underline{Z}_{0m}}$$

and \underline{K}_1 , \underline{L}_1 , \underline{M}_1 according to

$$5 \quad \underline{K}_1 = -\underline{Z}_{1LA}$$

$$\underline{L}_1 = \underline{Z}_{1LA} + \underline{Z}_{1sB}$$

$$\underline{M}_1 = \underline{Z}_{1sA} + \underline{Z}_{1sA} + \underline{Z}_{1LA}$$

15. A method according to claim 12, **characterised** by
 10 determining distance to a single ground fault using a first order formula (27a,b,c) of the form:

$$d = \frac{\text{imag}\{\underline{V}_{AA-p}[3(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})]^*\}}{\text{imag}\{(\underline{Z}_{1LA} \underline{I}_{AA-p})[3(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})]^*\}}$$

16. A method according to claim 12, **characterised** by
 15 determining distance to a phase-to-phase ground fault using pre-fault measurements and a first order formula (28a,b,c) of the form:

$$d = \frac{\text{imag}\{\underline{V}_{AA-p}[\underline{W}(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})]^*\}}{\text{imag}\{(\underline{Z}_{1LA} \underline{I}_{AA-p})[\underline{W}(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})]^*\}}$$

20 17. A method according to claim 12, **characterised** by determining distance to a phase-to-phase ground fault avoiding pre-fault measurements and using a first order formula (29a,b,c) of the form:

$$d = \frac{\text{imag}[(\underline{V}_a + \underline{V}_b)(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})^*]}{\text{imag}[\underline{Z}_{1LA}(\underline{I}_a + \underline{I}_b + 2\underline{k}_0 \underline{I}_{AA0} + 2\underline{k}_{0m} \underline{I}_{AB0})(\underline{I}_{AA0} - \underline{P}_0 \underline{I}_{AB0})^*]}$$

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18. A device for locating a fault from one end of a section of a power line (A-B) having means for receiving and storing measurements of current, voltage and angles between the phases at one first end (A), means for receiving and storing a
5 detection of a fault condition between said first and second ends (A,B), **characterised** by:
- means for calculating symmetrical components of currents for said current and voltage measured at said first end,
 - means for calculating a distance (d) from said first end (2)
10 to the fault (F).
19. A device according to claim 18, **characterised** by comprising:
- means for determining a value for source impedance at said
15 first end,
 - means for determining a value for source impedance at said second end.
20. A device according to any of claims 18-19, **characterised**
20 by comprising:
- means for receiving a measurement of source impedance at said first end A.
21. A device according to any of claims 18-20, **characterised**
25 by comprising:
- means for receiving a measurement of source impedance made at said second end B.
22. A device according to any of claims 18-21, **characterised**
30 by comprising means to receive a measured value (9) for remote source impedance at said second end (B) communicated by means of a communication channel (60).

23. Use of a fault locator device according to any of claims 18-22, by a human operator to supervise a function in an electrical power system.

24. Use of a fault locator device according to any of claims 18-22, by means of a process running on one or more computers to supervise and/or control a function in an electrical power system.

25. Use of a fault locator device according to any of claims 18-22, to locate a distance to a fault in a power transmission or distribution system.

26. Use of a device according to any of claims 18-22, for locating a fault on parallel power lines.

27. A computer program comprising computer code means and/or software code portions for making a computer or processor perform any of the steps of claims 1-17.

28. A computer program product according to claim 27 comprised in one or more computer readable media.

29. A data communication signal for locating a fault in a section of a power line included in a data transmission comprising a value of a measurement of source impedance made in respect of a remote and second (B) end of said section of a power line.

30. A graphic user interface for displaying a location of a fault in a section of a power line wherein a value is displayed for a distance (d) of said fault from a first end (A) of said power line.

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31. A graphic user interface according to claim 30,
characterised in that the value displayed for the distance (d)
is combined with a graphical representation of the relevant
power line section or network.

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32. A graphic user interface according to claim 30,
characterised in that the value displayed for the distance (d)
is arranged to be displayed upon activation of a part of the
graphical representation of the relevant power line section or
10 network using a computer mouse or similar computer display
selection means.